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# ***Parallel Computation Of Sensitivity Derivatives With Application to Aerodynamic Optimization of a Wing***

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# ***Outline***

- ***Introduction***
- ***Parallel Approach and Scaling***
- ***Parameterization And Design Variables***
- ***Comparison With Finite Differences***
- ***Wing Optimization***
- ***Summary***



# ***Introduction***

- ***For gradient-based optimization, need fast, accurate derivatives of objective functions and constraints***
- ***Code differentiation is exact and consistent with flow solver; tedious to do by hand, but automatic differentiation (AD) tools make it relatively simple***
- ***AD tools have been developed by Argonne National Laboratory and Rice University***
  - ***ADIFOR - differentiates code as it runs in “forward mode”***
  - ***ADJIFOR - differentiates code as it operates in “reverse mode” to mimic adjoint formulation***



## ***Introduction (cont.)***

- ***ADIFOR is mature technology - used for the current work; ADJIFOR has only recently been developed and is the focus of the next presentation***
- ***ADIFOR applied to the NASA Langley CFL3D code***
  - ***Solves Euler or Thin-Layer Navier Stokes***
  - ***Point match / patched / overset structured grids***
  - ***Steady state or time accurate***
- ***Computational cost of derivative calculation via ADIFOR roughly scales with  $N_{DV}$***
- ***Reduce wall time by using parallel processing***



# ***Parallel Approach***

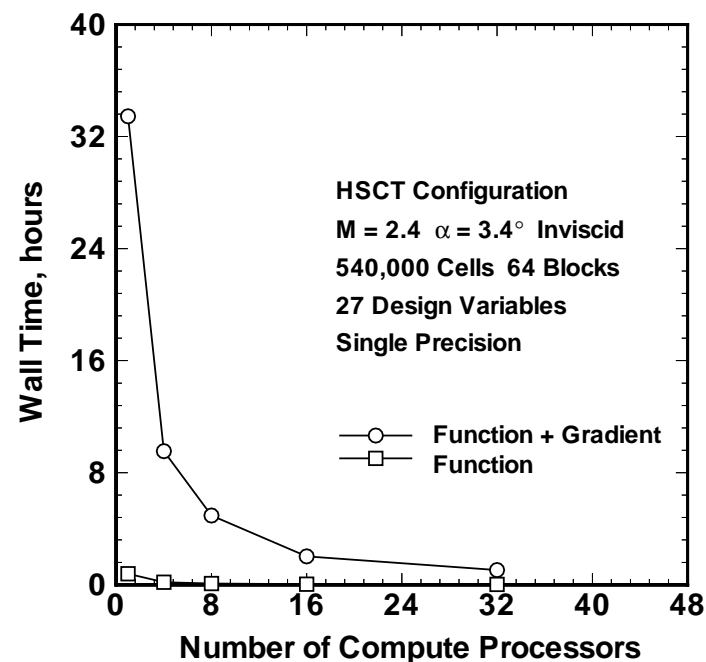
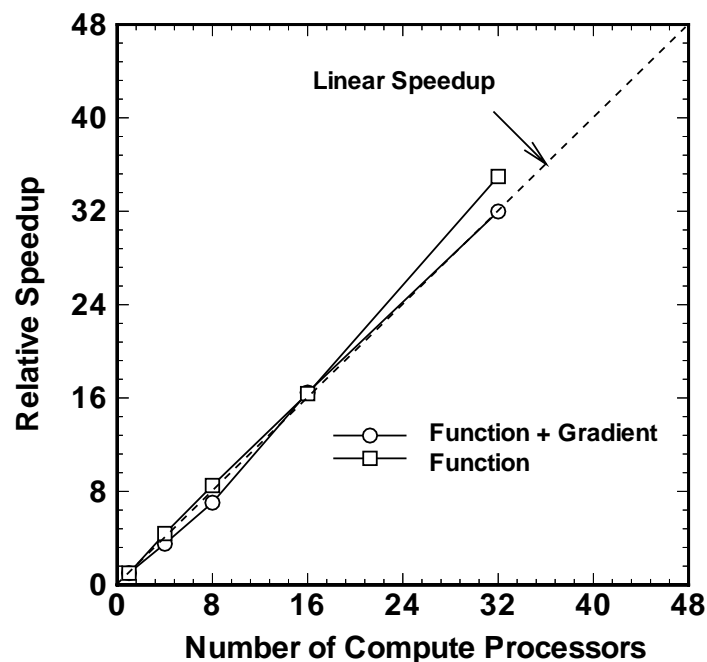
- ***Can utilize multiple processors to reduce wall time in two ways:***
  - ***“Coarse grain” parallelization by computing only a subset of  $N_{dv}$  on a CPU (not considered here)***
  - ***“Fine grain” parallelization by breaking the domain into a number of smaller blocks, and computing each block on a different CPU***
  - ***For large problems, can combine both methods***
- ***CFL3D (+AD) parallelized across blocks via MPI***
- ***For efficiency, parallel code must scale with number of CPUs***



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# Scaling

**1-32 Compute Processors on 195 Mhz Origin 2000**  
**HSCT Configuration 540,000 Grid Pts 27 DVs**





# ***Parameterization***

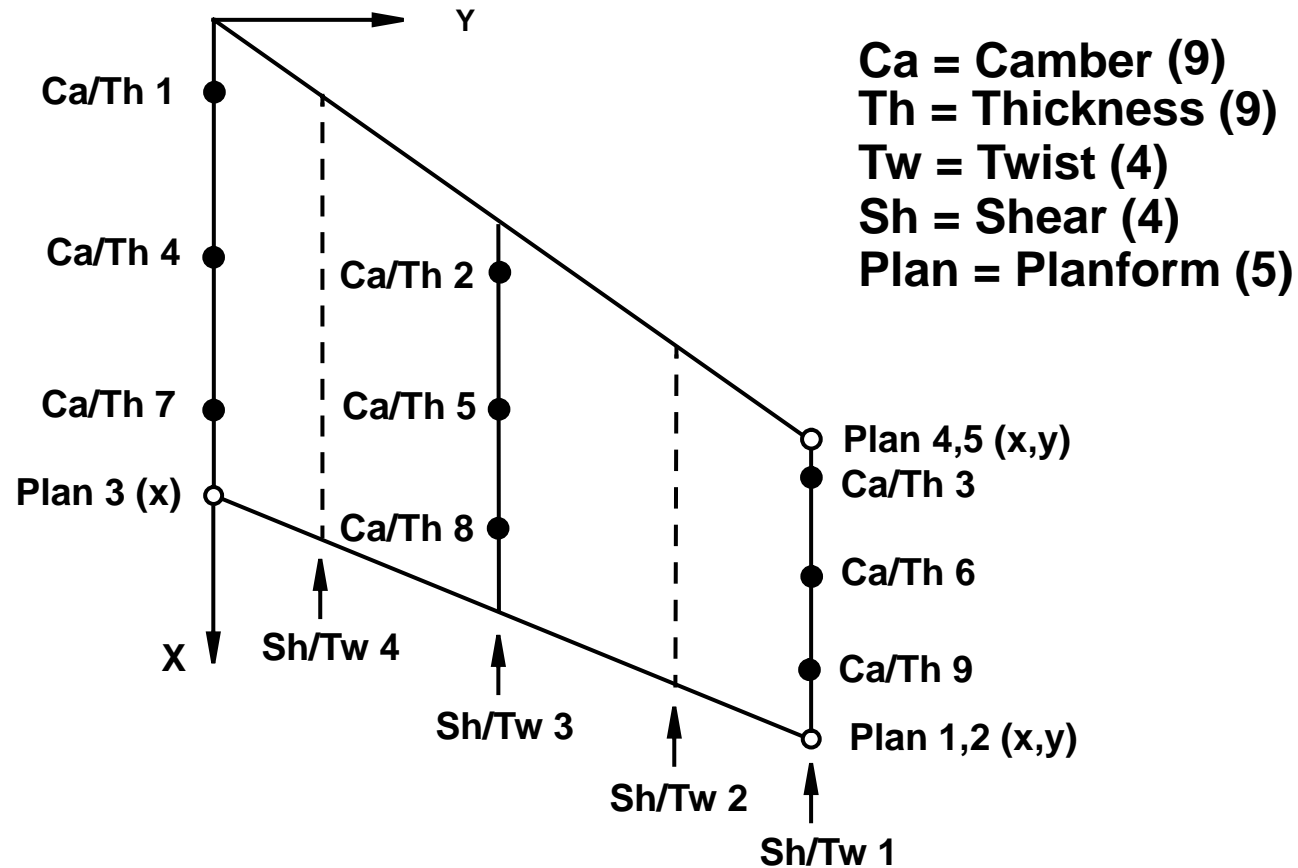
- ***New scheme developed by Samareh to parameterize existing CFD and CSM grids***
- ***Direct application to aero-structural interaction***
- ***Bezier net placed around baseline mesh***
- ***Control points can be used directly as design variables, or linked to design variables such as thickness, camber and twist***
- ***Mesh is “rubberized” and can be twisted, compressed, etc., but retains original topology***



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# Design Variables - ONERA M6

- *52 parameters used to define the surface mesh, 31 of these chosen as design variables:*







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# ***Comparison With Finite Differences***

***Central Finite Differences With  $h = 1 \times 10^{-6}$***

Derivative.	AD (DP)	FD (DP)	% error (DP)	AD (SP)
$dC_L/d(\text{Plan } 3)$	-0.08333	-0.08333	0.0	-0.08333
$dC_L/d(\text{Tw } 3)$	-0.02944	-0.02944	0.0	-0.02944
$dC_L/d(\text{Sh } 3)$	+0.02001	+0.02001	0.0	+0.02001
$dC_L/d(\text{Th } 8)$	<u>+0.43321</u>	+0.43321	0.0	<u>+0.43323</u>
$dC_L/d(\text{Ca } 8)$	+2.8380	+2.8380	0.0	+2.8380
$dC_D/d(\text{Plan } 3)$	-0.01065	-0.01065	0.0	-0.01065
$dC_D/d(\text{Tw}3)$	-0.00246	-0.00246	0.0	-0.00246
$dC_D/d(\text{Sh } 3)$	-0.00138	-0.00138	0.0	-0.00138
$dC_D/d(\text{Th } 8)$	+0.07016	+0.07016	0.0	+0.07016
$dC_D/d(\text{Ca } 8)$	+0.16467	+0.16467	0.0	+0.16467



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# ***Wing Optimization***

- ***Objective: reduce drag while maintaining same lift as baseline configuration***
- ***193x33x33 ONERA M6 wing with 31 DVs shown previously***
  - ***Planform variables constrained (area = const)***
  - ***Tip thickness variables constrained to prevent negative cell volumes at tip***
- ***DV bounds: twist +/- 1 deg., all others +/- 1% span***
- ***Flow solver, geometry perturbation codes, and optimizer coupled via UNIX scripts***

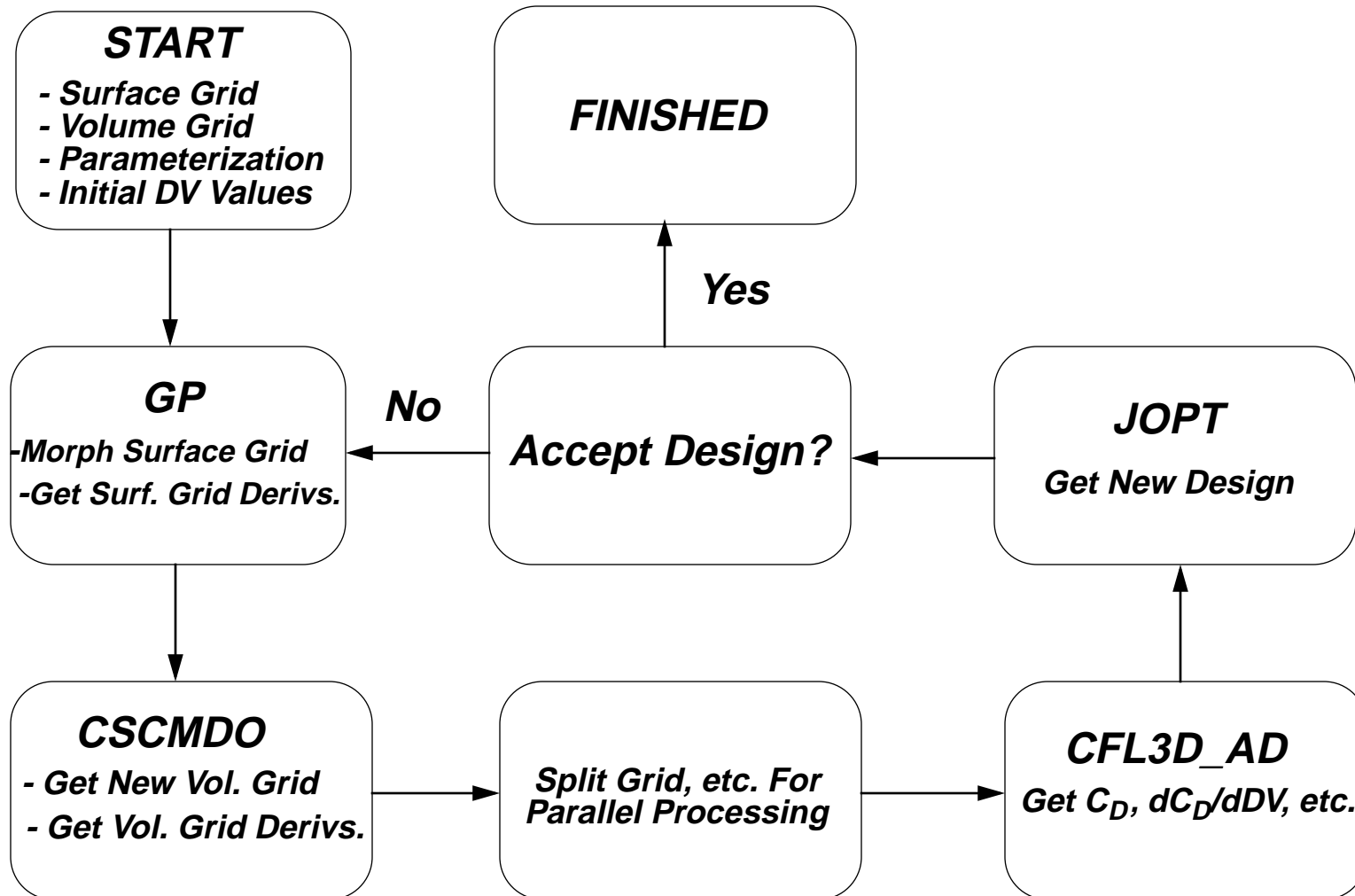


## ***Wing Optimization (cont.)***

- ***Optimizer: JOPT = CONMIN + linear approximation to objective function and constraints***
  - ***Linear approx. valid in a limited region around current solution***
  - ***Move limits introduced to keep within linear region; move limits typically  $\ll$  DV bounds***
- ***$\alpha$  not used as a design variable - optimizer would not move away from specified lift value***
  - ***Temporarily relax the lift constraint until minimum drag is reached***
  - ***Tighten constraint to target value for final design***



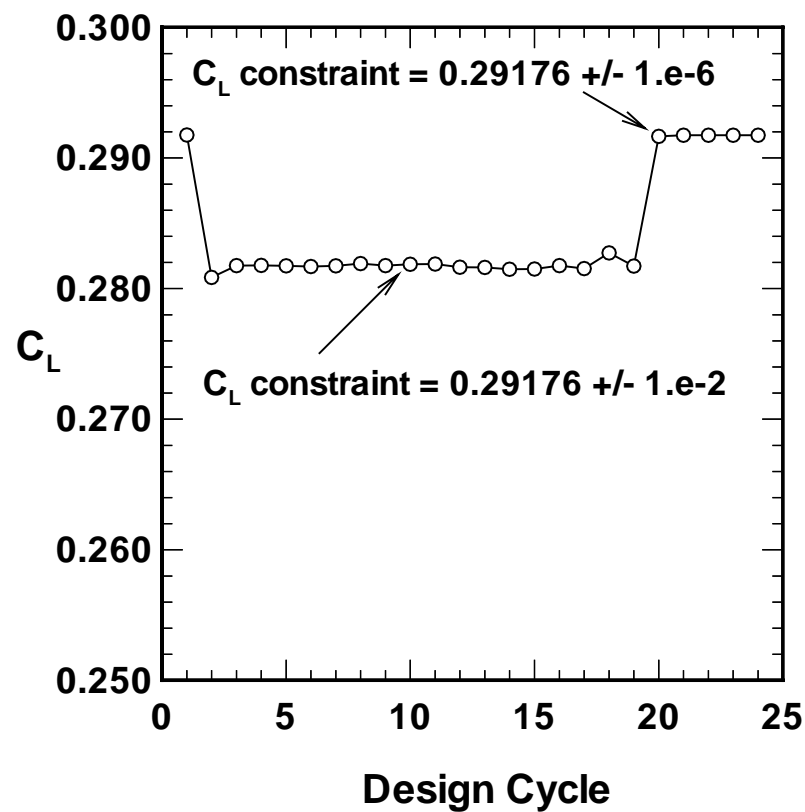
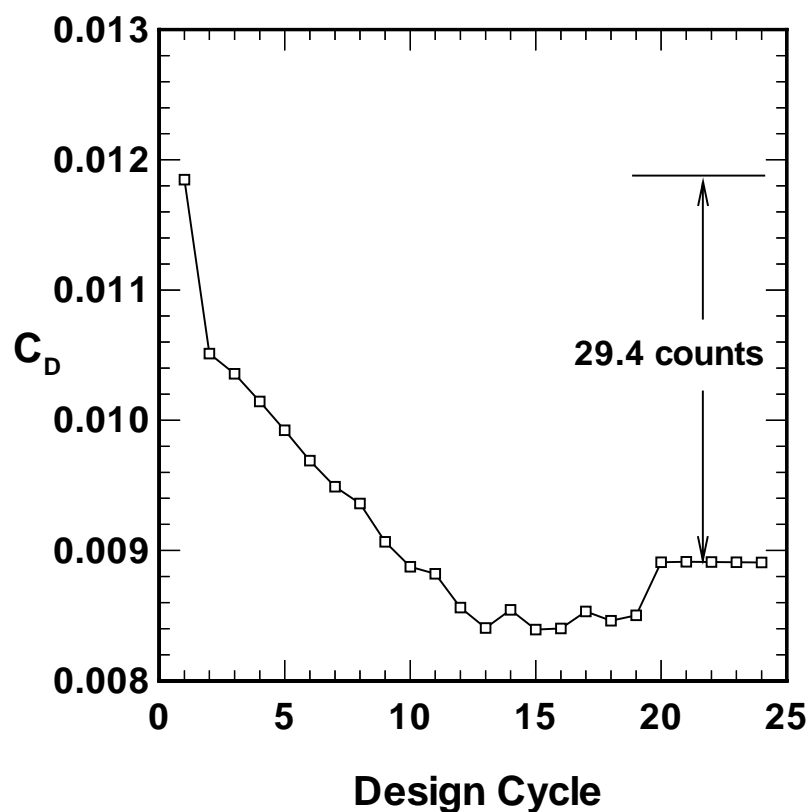
# Optimization Flowchart





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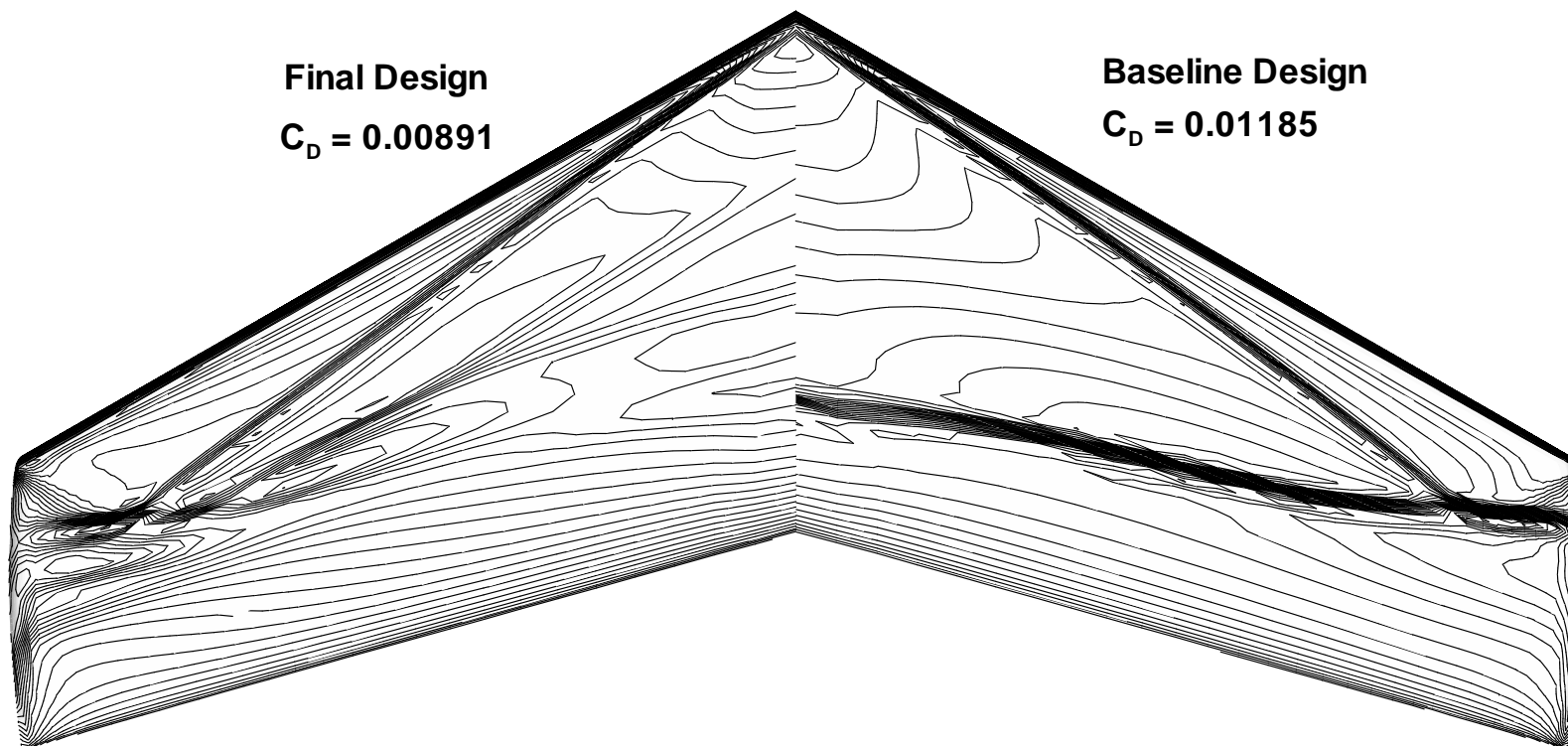
# Design Cycle History





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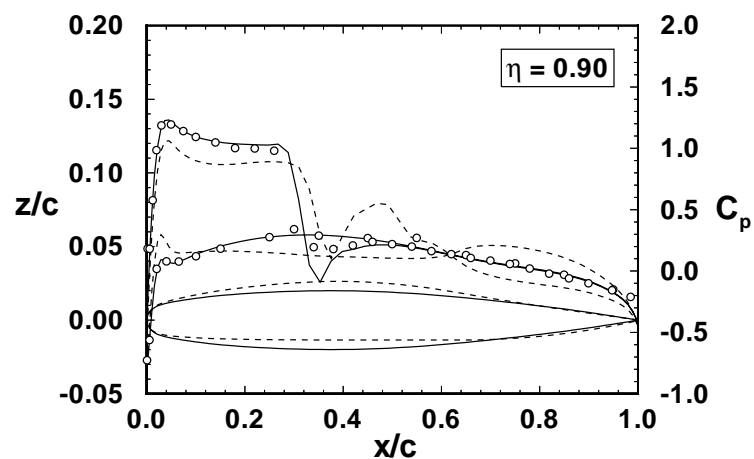
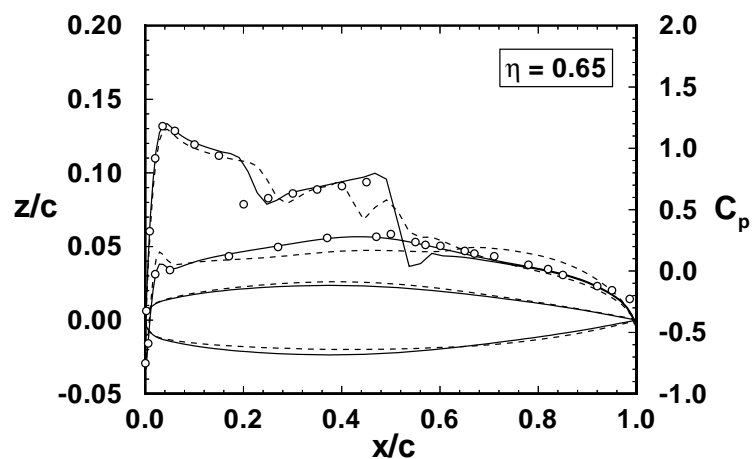
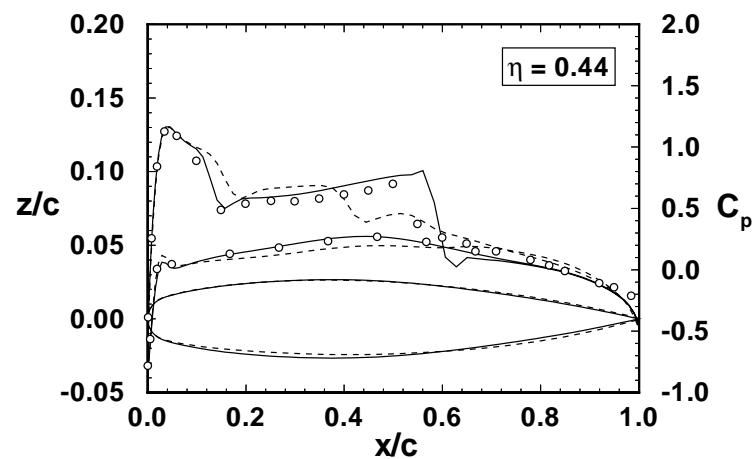
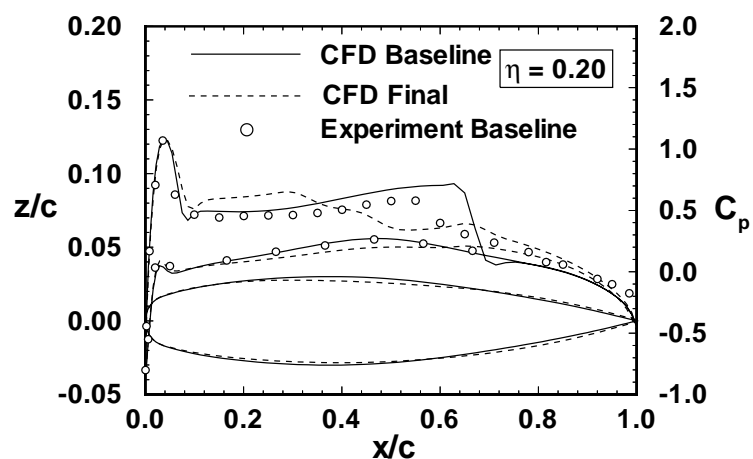
# ***Surface Pressures***





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# Pressure Coefficients / Wing Sections





# Summary

- ***ADIFOR applied to parallel version of CFL3D - AD derivatives demonstrated to be accurate***
- ***Parallel AD code shown to scale well with number of processors***
- ***Parallel AD code coupled with geometry and optimization packages for optimization problems***
- ***Demonstrated optimization package with 29 count drag reduction on inviscid M6 wing - also applied to HSCT optimization with 540k pts and 27 DVs***
- ***Future applications to include viscous flows***